

Log-Hilbert-Schmidt distance between covariance operators and its approximation

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One of the most commonly used Riemannian metrics on the set of symmetric, positive definite (SPD) matrices is the Log-Euclidean metric [1]. In this metric, the geodesic distance between two SPD matrices A and B is given by

$$d_{\log E}(A, B) = \|\log(A) - \log(B)\|_F, \quad (1)$$

where \log denotes the matrix principal logarithm.

Log-Hilbert-Schmidt distance. The generalization of the Log-Euclidean metric to the infinite-dimensional manifold $\Sigma(\mathcal{H})$ of positive definite Hilbert-Schmidt operators on a Hilbert space \mathcal{H} has recently been given by [2]. In this metric, termed *Log-Hilbert-Schmidt (Log-HS) metric*, the distance between two positive definite Hilbert-Schmidt operators $A + \gamma I > 0$ and $B + \mu I > 0$, $A, B \in \text{HS}(\mathcal{H})$, $\gamma, \mu > 0$, is given by

$$d_{\log \text{HS}}[(A + \gamma I), (B + \mu I)] = \|\log(A + \gamma I) - \log(B + \mu I)\|_{\text{eHS}}, \quad (2)$$

with the *extended Hilbert-Schmidt* norm defined by $\|A + \gamma I\|_{\text{eHS}}^2 = \|A\|_{\text{HS}}^2 + \gamma^2$.

RKHS covariance operators. As examples of positive Hilbert-Schmidt operators, consider covariance operators in reproducing kernel Hilbert spaces (RKHS), which play an important role in machine learning and statistics. Let \mathcal{X} be any non-empty set. Let K be a positive definite kernel on $\mathcal{X} \times \mathcal{X}$ and \mathcal{H}_K its induced RKHS. Let \mathcal{H} be any Hilbert feature space for K , assumed to be separable, which we identify with \mathcal{H}_K , with the corresponding feature map $\Phi : \mathcal{X} \rightarrow \mathcal{H}$, so that $K(x, y) = \langle \Phi(x), \Phi(y) \rangle_{\mathcal{H}}$ $\forall (x, y) \in \mathcal{X} \times \mathcal{X}$. Let $\mathbf{x} = [x_1, \dots, x_m]$ be a data matrix randomly sampled from \mathcal{X} according to some probability distribution. The feature map Φ gives the (potentially infinite) data matrix $\Phi(\mathbf{x}) = [\Phi(x_1), \dots, \Phi(x_m)]$ in \mathcal{H} . Formally, $\Phi(\mathbf{x})$ is a bounded linear operator $\Phi(\mathbf{x}) : \mathbb{R}^m \rightarrow \mathcal{H}$, defined by $\Phi(\mathbf{x})\mathbf{b} = \sum_{j=1}^m b_j \Phi(x_j)$, $\mathbf{b} \in \mathbb{R}^m$. The covariance operator for $\Phi(\mathbf{x})$ is defined by

$$C_{\Phi(\mathbf{x})} = \frac{1}{m} \Phi(\mathbf{x}) J_m \Phi(\mathbf{x})^* : \mathcal{H} \rightarrow \mathcal{H}, \quad J_m = I_m - \frac{1}{m} \mathbf{1}_m \mathbf{1}_m^T. \quad (3)$$

For $\gamma > 0, \mu > 0$, the Log-HS distance $d_{\log \text{HS}}[(C_{\Phi(\mathbf{x})} + \gamma I_{\mathcal{H}}), (C_{\Phi(\mathbf{y})} + \mu I_{\mathcal{H}})]$ between two regularized covariance operators $(C_{\Phi(\mathbf{x})} + \gamma I_{\mathcal{H}})$ and $(C_{\Phi(\mathbf{y})} + \mu I_{\mathcal{H}})$

$$d_{\log \text{HS}} = \|\log(C_{\Phi(\mathbf{x})} + \gamma I_{\mathcal{H}}) - \log(C_{\Phi(\mathbf{y})} + \mu I_{\mathcal{H}})\|_{\text{eHS}} \quad (4)$$

has a closed form in terms of the corresponding Gram matrices [2]. This distance is generally computationally intensive for large m , however.

Approximation by finite-dimensional Log-Euclidean distances. To reduce the computational cost, we consider computing an *explicit approximate feature map* $\hat{\Phi}_D : \mathcal{X} \rightarrow \mathbb{R}^D$, where D is finite and $D \ll \dim(\mathcal{H})$, so that

$$\langle \hat{\Phi}_D(x), \hat{\Phi}_D(y) \rangle_{\mathbb{R}^D} = \hat{K}_D(x, y) \approx K(x, y), \quad \text{with } \lim_{D \rightarrow \infty} \hat{K}_D(x, y) = K(x, y), \quad (5)$$

$\forall (x, y) \in \mathcal{X} \times \mathcal{X}$. With the approximate feature map $\hat{\Phi}_D$, we have the matrix $\hat{\Phi}_D(\mathbf{x}) = [\hat{\Phi}_D(x_1), \dots, \hat{\Phi}_D(x_m)] \in \mathbb{R}^{D \times m}$ and the approximate covariance operator

$$C_{\hat{\Phi}_D(\mathbf{x})} = \frac{1}{m} \hat{\Phi}_D(\mathbf{x}) J_m \hat{\Phi}_D(\mathbf{x})^T : \mathbb{R}^D \rightarrow \mathbb{R}^D. \quad (6)$$

We then consider the following as an approximate version of the Log-HS distance given in Formula (4):

$$\left\| \log \left(C_{\hat{\Phi}_D(\mathbf{x})} + \gamma I_D \right) - \log \left(C_{\hat{\Phi}_D(\mathbf{y})} + \mu I_D \right) \right\|_F. \quad (7)$$

Key theoretical question. We need to determine whether Formula (7) is truly a finite-dimensional approximation of Formula (4), in the sense that

$$\begin{aligned} \lim_{D \rightarrow \infty} \left\| \log(C_{\hat{\Phi}_D(\mathbf{x})} + \gamma I_D) - \log(C_{\hat{\Phi}_D(\mathbf{y})} + \mu I_D) \right\|_F \\ = \left\| \log(C_{\Phi(\mathbf{x})} + \gamma I_{\mathcal{H}}) - \log(C_{\Phi(\mathbf{y})} + \mu I_{\mathcal{H}}) \right\|_{\text{eHS}}. \end{aligned} \quad (8)$$

The following results shows that in general, this is *not* possible.

Theorem 1. *Assume that $\gamma \neq \mu$, $\gamma > 0$, $\mu > 0$. Then*

$$\lim_{D \rightarrow \infty} \left\| \log(C_{\hat{\Phi}_D(\mathbf{x})} + \gamma I_D) - \log(C_{\hat{\Phi}_D(\mathbf{y})} + \mu I_D) \right\|_F = \infty.$$

In practice, however, it is reasonable to assume that we can use the same regularization parameter for both $C_{\hat{\Phi}_D(\mathbf{x})}$ and $C_{\hat{\Phi}_D(\mathbf{y})}$, that is to set $\gamma = \mu$. In this setting, we obtain the necessary convergence, as follows.

Theorem 2. *Assume that $\gamma = \mu > 0$. Then*

$$\begin{aligned} \lim_{D \rightarrow \infty} \left\| \log(C_{\hat{\Phi}_D(\mathbf{x})} + \gamma I_D) - \log(C_{\hat{\Phi}_D(\mathbf{y})} + \gamma I_D) \right\|_F \\ = \left\| \log(C_{\Phi(\mathbf{x})} + \gamma I_{\mathcal{H}}) - \log(C_{\Phi(\mathbf{y})} + \gamma I_{\mathcal{H}}) \right\|_{\text{eHS}}. \end{aligned} \quad (9)$$

References

- [1] Arsigny, V., Fillard, P., Pennec, X. and Ayache, N., 2007. Geometric means in a novel vector space structure on symmetric positive-definite matrices. *SIAM journal on matrix analysis and applications*, 29(1), pp.328-347.
- [2] Minh, H.Q., San Biagio, M. and Murino, V., 2014. Log-Hilbert-Schmidt metric between positive definite operators on Hilbert spaces. In *Advances in Neural Information Processing Systems* (pp. 388-396).